

# MAE 286: Hybrid Systems (W14)

## Homework #6

Due on 2/25/14

1. Consider the hybrid system with data  $C = \mathbb{R}, D = \emptyset$ ,

$$F(x) = \begin{cases} 1 & x < 0 \\ 2 & x \geq 0 \end{cases}$$

and any  $G$  you want. Does this system satisfy the basic assumptions? Is it well-posed?

2. Construct an example of a hybrid automaton that has unstable dynamics in each of its 2 discrete modes, but for which the equilibrium  $x_e = 0$  is globally stable. Plot a phase portrait of your system.
3. Consider the hybrid system  $\mathcal{H}$  with state  $x \in \mathbb{R}^2$  and data

$$\begin{aligned} C &:= \{x \in \mathbb{R}^2 \mid \|x\| < 1\}, & f(x) &:= \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix} \\ D &:= \{x \in \mathbb{R}^2 \mid x_1 = 0, x_2 \in (-\frac{1}{2}, 0]\}, & g(x) &:= \frac{1}{2}x \end{aligned}$$

Answer the following questions, properly justifying your response in each case:

- Is the set  $A = \{(0, 0)\}$  uniformly globally stable? Is  $A$  UGpAS?
  - Is the set  $A = \{x \in \mathbb{R}^2 \mid \|x\| = \frac{1}{2}\}$  uniformly globally stable? Is  $A$  UGpAS?
4. This exercise introduces you to the Hybrid Equations (HyEq) Matlab Toolbox toolbox developed for the modeling framework studied in class. The code and instructions are available at <http://www.mathworks.com/matlabcentral/fileexchange/41372-hybrid-equations-toolbox-v2-0>. You can get familiarized with the toolbox by watching a 30-min webinar at <https://www.mathworks.com/videos/hyeq-a-toolbox-for-simulation-of-hybrid-dynamical-systems-81992.html>.

Once you are familiar with it, let us use it! Hysteresis is a key player in genetic regulatory networks. Consider the following descriptive model of a genetic regulatory network in the mammalian sclera. The state is

$$z = (x_1, x_2, x_3, q_1, q_2, q_3, q_4) \in Z = \mathbb{R}_{\geq 0}^3 \times \{0, 1\}^4$$

Here,  $x_1$  represents the protein concentration of TIMP-2 (Type II tissue inhibitor of the matrix metalloproteinases),  $x_2$  the concentration of MT1-MMP (membrane-type I matrix metalloproteinase), and  $x_3$  the concentration of MMP-2 (Type II matrix metalloproteinase). The discrete states  $q_1, q_2, q_3, q_4$  define different modes depending on whether protein concentrations have reached large enough values to express or inhibit other proteins.

For the continuous flow, positive constants  $\gamma_1, \gamma_2, \gamma_3$  define the decay rates and  $k_1, k_2, k_3$  define the growth rates, respectively, for each of the concentrations. For the jumps, hysteresis functions are associated with the thresholds  $\theta_1$  (TIMP-2 level for MT1-MMP expression),  $\theta_2$  (MT1-MMP level for MMP-2 expression),  $\theta_3$  (TIMP-2 level for MT1-MMP/MMP-2 inhibition), and  $\theta_4$  (4 MMP-2 level for TIMP-2 expression), and a hysteresis half-width constant  $h_i$  is associated with each threshold.

In this way, the flow map is given by

$$F(z) = \begin{pmatrix} k_1 q_4 - \gamma_1 x_1 \\ k_2 q_1 (1 - q_3) - \gamma_2 x_2 \\ k_3 q_2 (1 - q_3) - \gamma_3 x_3 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

The jump set is  $D = D_1 \cup D_2 \cup D_3 \cup D_4$ , where

$$\begin{aligned} D_1 &= \{z \in Z \mid q_1 = 1, x_1 \leq \theta_1 - h_1\} \cup \{z \in Z \mid q_1 = 0, x_1 \geq \theta_1 + h_1\} \\ D_2 &= \{z \in Z \mid q_2 = 1, x_2 \leq \theta_2 - h_2\} \cup \{z \in Z \mid q_2 = 0, x_2 \geq \theta_2 + h_2\} \\ D_3 &= \{z \in Z \mid q_3 = 1, x_3 \leq \theta_3 - h_3\} \cup \{z \in Z \mid q_3 = 0, x_3 \geq \theta_3 + h_3\} \\ D_4 &= \{z \in Z \mid q_4 = 1, x_4 \leq \theta_4 - h_4\} \cup \{z \in Z \mid q_4 = 0, x_4 \geq \theta_4 + h_4\} \end{aligned}$$

and the flow set is  $C = \overline{Z \setminus D}$ . Finally, the jump map is

$$G(z) = \begin{cases} g_1(z) & z \in D_1 \setminus (D_2 \cup D_3 \cup D_4) \\ g_2(z) & z \in D_2 \setminus (D_1 \cup D_3 \cup D_4) \\ g_3(z) & z \in D_3 \setminus (D_1 \cup D_2 \cup D_4) \\ g_4(z) & z \in D_4 \setminus (D_1 \cup D_2 \cup D_3) \\ \{g_1(z), g_2(z), g_3(z), g_4(z)\} & z \in D_1 \cap D_2 \cap D_3 \cap D_4, \end{cases}$$

where,

$$\begin{aligned} g_1(z) &= (x_1, x_2, x_3, 1 - q_1, q_2, q_3, q_4) \\ g_2(z) &= (x_1, x_2, x_3, q_1, 1 - q_2, q_3, q_4) \\ g_3(z) &= (x_1, x_2, x_3, q_1, q_2, 1 - q_3, q_4) \\ g_4(z) &= (x_1, x_2, x_3, q_1, q_2, q_3, 1 - q_4). \end{aligned}$$

Let the thresholds be given by  $\theta_1 = 0.4, \theta_2 = 0.5, \theta_3 = 0.6, \theta_4 = 0.7$ , with associated half-width constants  $h_j = 0.01, j \in \{1, 2, 3, 4\}$ . Also, let the decay rates be  $\gamma_i = 1, i \in \{1, 2, 3\}$ . Simulate the following scenarios:

- (i)  $k_1 = 1, i \in \{1, 2, 3\}$ ; and initial condition  $x_1(0) = 0.15, x_2(0) = 0.45, x_3(0) = 0.8, q_1(0) = 1, q_2(0) = 1, q_3(0) = 0, q_4(0) = 1$ .
- (ii)  $k_1 = .55, k_2 = 1, k_3 = 0.9$ ; and initial condition  $x_1(0) = 0.45, x_2(0) = 0.6, x_3(0) = 0.8, q_1(0) = 1, q_2(0) = 1, q_3(0) = 0, q_4(0) = 1$ .
- (iii)  $k_1 = 1, i \in \{1, 2, 3\}$ ; and initial condition  $x_1(0) = 0.45, x_2(0) = 0.45, x_3(0) = 0.8, q_1(0) = 1, q_2(0) = 1, q_3(0) = 0, q_4(0) = 1$ .

For each scenario, describe what is the limiting behavior that you observe.